

# 8k bit EEPROM for direct connection to serial ports

The BH9080F are serial EEPROMs that can be connected directly to a serial port and can be erased and written electrically. Writing and reading is performed in word units, using four types of operation commands. Communication occurs through  $\overline{CS}$ ,  $\overline{SK}$ , DI, and DO pins,  $\overline{WC}$  pin control is used to initiate a write disabled state, enabling these EEPROMs to be used as one-time ROMs. During writing, operation is checked via the internal status check.

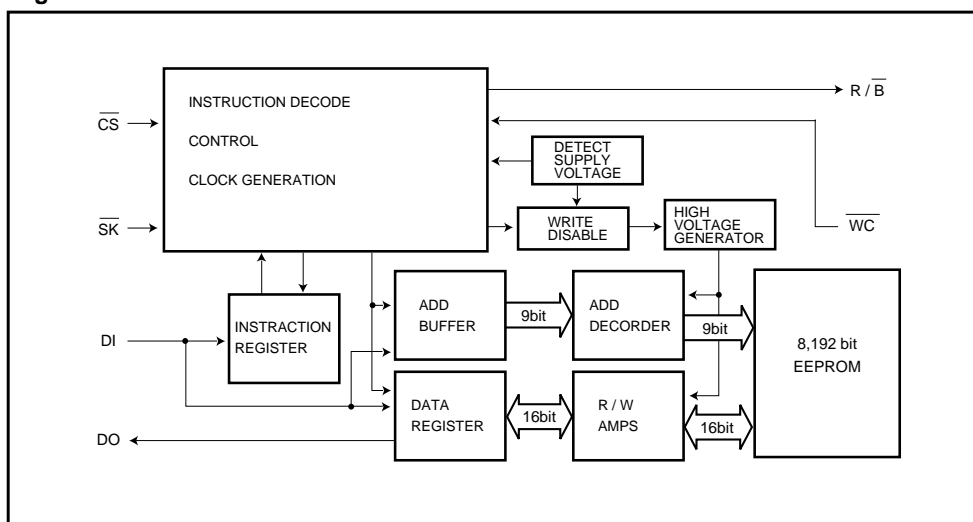
## ●Applications

Movie, camera, cordless telephones, car stereos, VCRs, TVs, DIP switches, and other battery-powered equipment requiring low voltage and low current

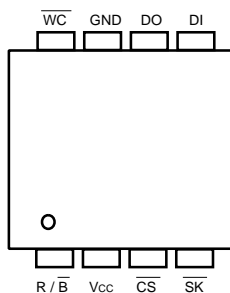
## ●Features

- 1) BR9080 / F / RFV (8k bit): 512 words × 16 bits
- 2) Single power supply operation
- 3) Serial data input and output
- 4) Automatic erase-before-write
- 5) Low current consumption  
Active (3.3V) : 5mA (max.)  
Standby (3.3V) : 3uA
- 6) Noise filter built into SK pin
- 7) Write protection when  $V_{CC}$  is low
- 8) Compact DIP8 / SOP8 / SSOP-B8 packages
- 9) High reliability CMOS process
- 10) 100,000 ERASE / WRITE cycles
- 11) 10 years Data Retention

## ●Block diagram



## ●Pin descriptions



BH9080F : SOP8

Fig.1

Pin No.		Pin name	Function
DIP / SSOP	SOP		
1	3	$\overline{CS}$	Chip Select Control
2	4	$\overline{SK}$	Serial Data Clock Input
3	5	DI	Op code, address, Serial Data Input
4	6	DO	Serial Data Output
5	7	GND	Ground 0V
6	8	$\overline{WC}$	Write Control Input
7	1	R / $\overline{B}$	READY / $\overline{BUSY}$ Output
8	2	V <sub>cc</sub>	Power supply

## ●Absolute maximum ratings (Ta=25°C)

Parameter	Symbol	Limits		Unit
Supply voltage	V <sub>cc</sub>	-0.3~+3.6		V
Power dissipation	Pd	SOP8	350*2	mW
Storage temperature	T <sub>stg</sub>	-65~+125		°C
Operation temperature	T <sub>opr</sub>	-40~+85		°C
Input voltage	-	-0.3~V <sub>cc</sub> +0.3		V

\*1 Reduced by 5.0mW for each increase in Ta of 1°C over 25°C.

\*2 Reduced by 3.5mW for each increase in Ta of 1°C over 25°C.

\*3 Reduced by 3.0mW for each increase in Ta of 1°C over 25°C.

## ●Recommended operating conditions (Ta=25°C)

Parameter	Symbol	Min.	Typ.	Max.	Unit
Power supply voltage	WRITE	2.7	-	3.6	V
	READ	2.7	-	3.6	V
Input voltage	V <sub>IN</sub>	0	-	V <sub>cc</sub>	V

## ●Electrical characteristics

BH9080F RFV: 3V (Unless otherwise noted, Ta= -40~85°C, Vcc=2.7V~3.6V)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Input low level voltage 1	V <sub>IL1</sub>	–	–	0.3×V <sub>CC</sub>	V	DI pin
Input high level voltage 1	V <sub>IH1</sub>	0.7×V <sub>CC</sub>	–	–	V	DI pin
Input low level voltage 2	V <sub>IL2</sub>	–	–	0.2×V <sub>CC</sub>	V	$\overline{CS}$ , $\overline{SK}$ , $\overline{WC}$ pin
Input high level voltage 2	V <sub>IH2</sub>	0.8×V <sub>CC</sub>	–	–	V	$\overline{CS}$ , $\overline{SK}$ , $\overline{WC}$ pin
Output low level voltage	V <sub>OL</sub>	0	–	0.4	V	I <sub>OL</sub> =100μA
Output high level voltage	V <sub>OH</sub>	V <sub>CC</sub> -0.4	–	V <sub>CC</sub>	V	I <sub>OH</sub> =-100μA
Input leak current	I <sub>LI</sub>	-1	–	1	μA	V <sub>IN</sub> =0V~V <sub>CC</sub>
Output leak current	I <sub>LO</sub>	-1	–	1	μA	V <sub>OUT</sub> =0V~V <sub>CC</sub> , $\overline{CS}$ =V <sub>CC</sub>
Consumption current during operation	I <sub>CC1</sub>	–	–	3	mA	f <sub>SK</sub> =2MHz tE / W=10ms (WRITE)
	I <sub>CC2</sub>	–	–	750	μA	f <sub>SK</sub> =2MHz (READ)
Standby current	I <sub>SB</sub>	–	–	2	μA	$\overline{CS}$ / $\overline{SK}$ / DI / $\overline{WC}$ =V <sub>CC</sub> DO, R / $\overline{B}$ =OPEN
$\overline{SK}$ frequency	f <sub>SK</sub>	–	–	2	MHz	–

© Not designed for radiation resistance

### ●Operating timing characteristics

BH9080F (Unless otherwise noted,  $T_a = -40 \sim 85^\circ\text{C}$ ,  $V_{CC} = 2.7\text{V} \sim 3.6\text{V}$ )

Parameter	Symbol	Min.	Typ.	Max.	Unit
CS setup time	$t_{CSS}$	100	–	–	ns
CS hold time	$t_{CSH}$	100	–	–	ns
Data setup time	$t_{DIS}$	100	–	–	ns
Data hold time	$t_{DIH}$	100	–	–	ns
DO rise delay time	$t_{PD1}$	–	–	150	ns
DO fall delay time	$t_{PD0}$	–	–	150	ns
Self-timing programming cycle	$t_E / W$	5	–	10	ms
CS minimum high level time	$t_{CS}$	250	–	–	ns
READY / $\overline{\text{BUSY}}$ display valid time	$t_{SV}$	–	–	150	ns
Time when DO goes HIGH-Z (via CS)	$t_{OH}$	0	–	150	ns
Data clock high level time	$t_{WH}$	250	–	–	ns
Data clock low level time	$t_{WL}$	250	–	–	ns
Write control setup time	$t_{WCS}$	0	–	–	ns
Write control hold time	$t_{WCH}$	0	–	–	ms

### ●Timing chart

Synchronous Data Input Output Timing

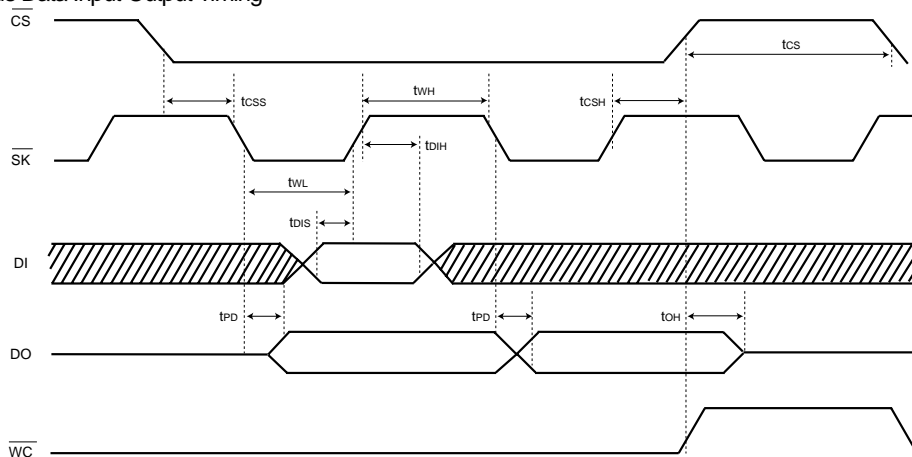


Fig.2

- Input data are clocked in to DI at the rising edge of the clock ( $\overline{\text{SK}}$ ).
- Output data will toggle on the falling edge of the  $\overline{\text{SK}}$  clock.
- The WC pin does not have any effect on the READ, EWEN and EWDS operations.

●Circuit operation

(1) Command mode

BH9080F

Instruction	Start Bit	Op Code	Address	Data
Read (READ)	1010	100 A0	A1 A2 A3 A4 A5 A6 A7 A8	
Write (WRITE)	1010	010 A0	A1 A2 A3 A4 A5 A6 A7 A8	D0 D1 – D14 D15
Erase / Write enable (EWEN)	1010	0011	* * * * * * * *	
Erase / Write disable (EWDS)	1010	0000	* * * * * * * *	

\* : Means either VIH or VIL  
Address and data are transferred from LSB.

(2) Writing enabled / disabled

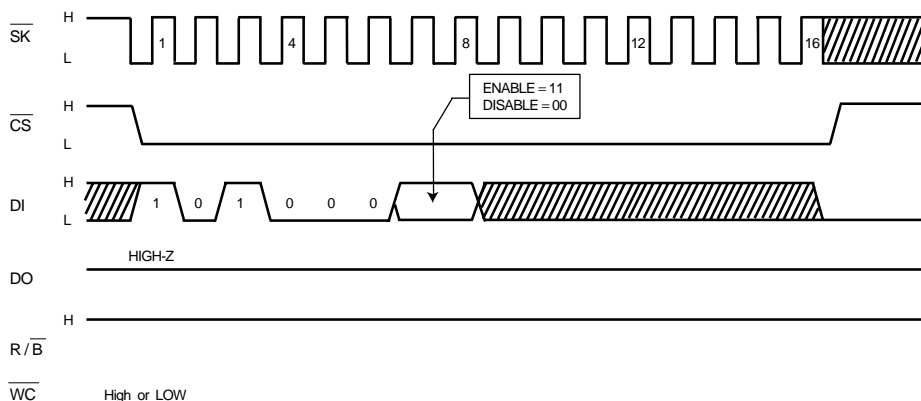


Fig.3

- 1) When  $\overline{CS}$  is "HIGH" during power up, BH9080F comes up in the erase / write disabled (EWDS) state. In order to be programmable, it must receive an enable (EWEN) instruction. The device remains programmable until a disable (EWDS) instruction is entered, or until it is powered down.
- 2) It is unnecessary to add the clock after 16th clock.

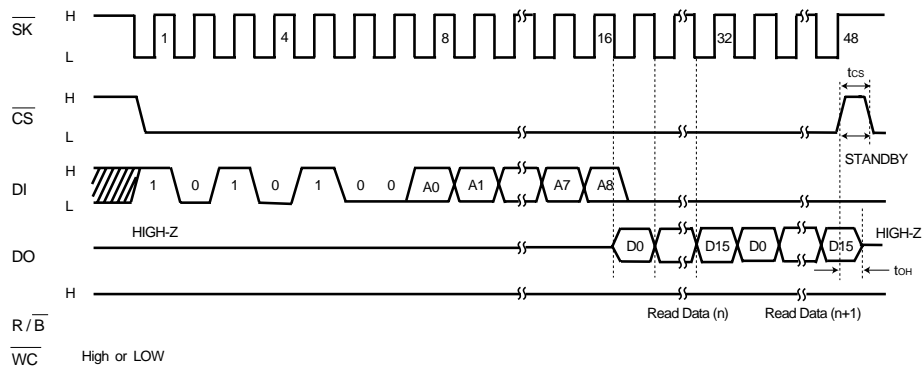
(3) Read cycle  
BH9080F

Fig.4 BH9080F

1) After the fall of the 16th clock pulse, 16-bit data is output from the DO pin in synchronization with the falling edge of the SK signal.

(DO output changes at a time lag of  $t_{PD0}$ ,  $t_{PD1}$  because of internal circuit delay following the falling edge of the SK signal. During the  $t_{PD0}$  and  $t_{PD1}$  timing, the  $t_{PD}$  time should be assured before data is read, to avoid the previous data being lost. See the synchronized data input / output timing chart in Fig.2.)

2)

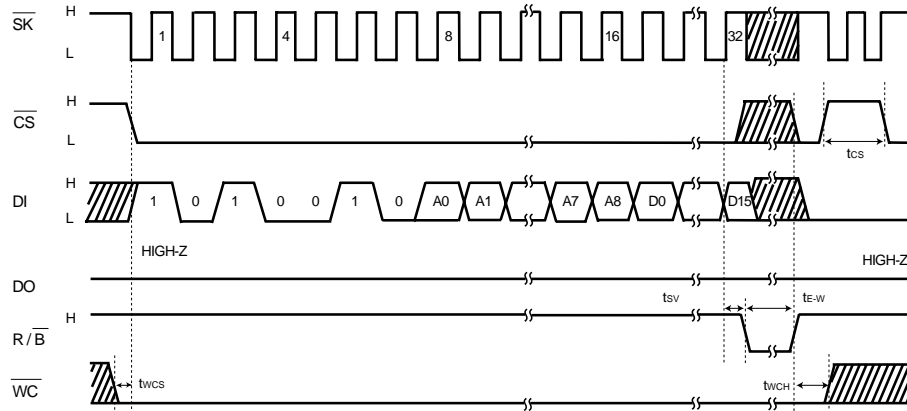
(4) Write cycle  
BH9080F

Fig.6 BH9080F

- 1) At the rising edge of 32nd clock,  $\overline{R/B}$  pin will be come out "LOW" after the specified time delay ( $t_{sv}$ ).
- 2) From above edge  $\overline{R/B}$  will indicate the ready / busy status of the chip: "LOW" indicated programming is all in progress: "HIGH" indicates the write cycle is complete and this part is ready for another instruction.
- 3) During the input of Write command,  $\overline{CS}$  must be "LOW". However, once the write operation started,  $\overline{CS}$  could be either "HIGH" or "LOW".
- 4) If  $\overline{WC}$  becomes "HIGH" during Write Cycle, the write operation is halted. In this case, the address data in writing is no guaranteed. It is necessary to rewrite it.

(5) READY /  $\overline{\text{BUSY}}$  display (R /  $\overline{\text{B}}$  pin and DO pin: BH9080F)

- 1) This display outputs the internal status signal; the R /  $\overline{\text{B}}$  pin outputs the HIGH or LOW status at all times. The display can also be output from the DO pin. Following completion of the writing command, if  $\overline{\text{CS}}$  falls while  $\overline{\text{SK}}$  is LOW, either HIGH or LOW is output. (The display can also be output without using the R /  $\overline{\text{B}}$  pin, leaving it open.)
- 2) When writing data to a memory cell, the READY /  $\overline{\text{BUSY}}$  display is output from the rise of the 32nd clock pulse of the  $\overline{\text{SK}}$  signal after  $t_{sv}$ , from the R /  $\overline{\text{B}}$  pin.

R /  $\overline{\text{B}}$  display = LOW: writing in progress

(The internal timer circuit is activated, and after the  $t_{E/W}$  timing has been created, the timer circuit stops automatically. Writing of data to the memory cell is done during the  $t_{E/W}$  timing, during which time other commands cannot be received.)

R /  $\overline{\text{B}}$  display = HIGH: command standby state

(Writing of data to the memory cell has been completed and the next command can be received.)

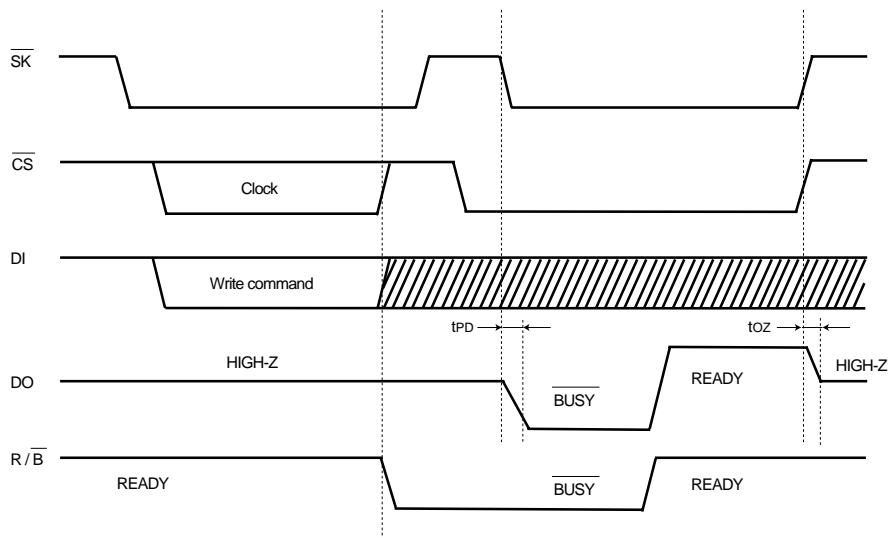


Fig.8 R /  $\overline{\text{B}}$  Status Output timing chart

- 1) DO will output R /  $\overline{\text{B}}$  status after  $\overline{\text{CS}}$  is held low during  $\overline{\text{SK}}=\text{L}$ , until  $\overline{\text{CS}}$  is held high.

Note : The document may be strategic technical data subject to COCOM regulations.



### ●Operation notes

(1) Turning the power supply on and off

1) When the power supply is turned on and off,  $\overline{CS}$  should be set to HIGH (=V<sub>CC</sub>).

2) When  $\overline{CS}$  is LOW, the command input reception state (active) is entered. If the power supply is turned on in this state, erroneous operations and erroneous writing can occur because of noise and other factors. To avoid this, make sure  $\overline{CS}$  is set to HIGH (=V<sub>CC</sub>) before turning on the power supply.

(Good example) Here, the  $\overline{CS}$  pin is pulled up to V<sub>CC</sub>.

When turning off the power supply, wait at least 10msec before turning it on again. Failing to observe this condition can result in the internal circuit failing to be reset when the power supply is turned on.

(Bad example)  $\overline{CS}$  is LOW when the power supply is turned on or off.

In this case, because  $\overline{CS}$  remains LOW, the EEPROM may perform erroneous operations or write erroneous data because of noise or other factors.

\* Please be aware that the case shown in this example can also occur if  $\overline{CS}$  input is HIGH-Z.

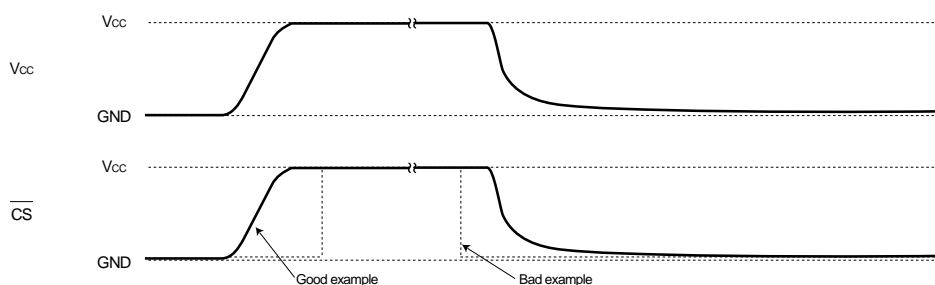


Fig.9

(2) Noise countermeasures

1)  $\overline{SK}$  noise

If noise occurs at the rise of the  $\overline{SK}$  clock input, the clock is assumed to be excessive, and this can cause malfunction because the bits are out of alignment.

2)  $\overline{WC}$  noise

During a writing operation, noise at the  $\overline{WC}$  pin can be erroneously judged to be data, and this can cause writing to be forcibly interrupted.

3) V<sub>CC</sub> noise

Noise and surges on the power supply line can cause malfunction. We recommend installing a bypass capacitor between the power supply and ground to eliminate this problem.

## (3) Canceling modes

## 1) Read commands

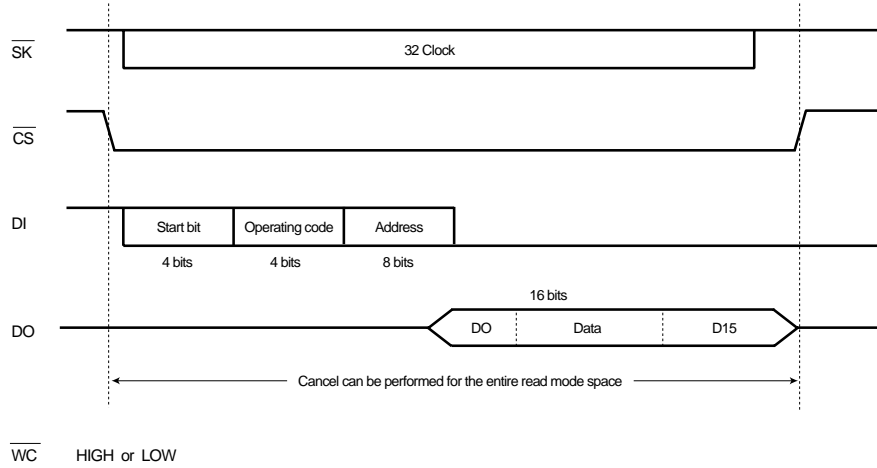


Fig.10

Cancellation method:  $\overline{CS}$  HIGH

## 2) Write commands

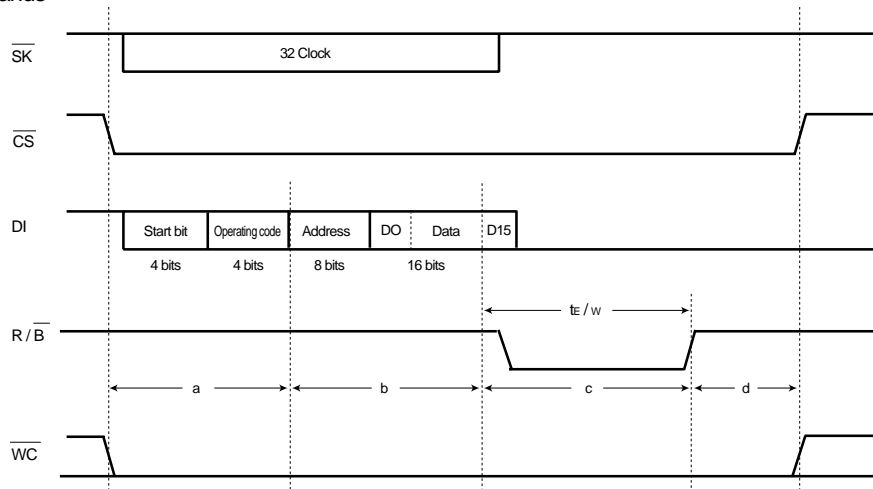


Fig.11

## Canceling methods

a : Canceled by setting  $\overline{CS}$  HIGH. The  $\overline{WC}$  pin is not involved.

b : If the  $\overline{WC}$  pin goes HIGH for even a second, writing is forcibly interrupted. Cancellation occurs even if the  $\overline{CS}$  pin is HIGH. At this point, data has not been written to the memory, so the data in the designated address has not yet been changed.

c : The operation is forcibly canceled by setting the  $\overline{WC}$  pin to HIGH or turning off the power supply (although we do not recommend using this method). The data in the designated address is not guaranteed and should be written once again.

d : If  $\overline{CS}$  is set to HIGH while the  $R/\overline{B}$  signal is HIGH (following the  $t_{E/W}$  timing), the IC is reset internally, and waits for the next command to be input.

●External dimension (Units : mm)

